# CHAPTER TWO

# **METHOD OF LEAST WORK**

The method of least work is used for the analysis of statically indeterminate beams, frames and trusses. Indirect use of the Castigliano's 2nd theorem is made and the following steps are taken.

- (1) The structure is considered under the action of applied loads and the redundants. The redundants can be decided by choosing a particular basic determinate structure and the choice of redundants may vary within a problem.
- (2) Moment expressions for the entire structure are established in terms of the applied loads and the redundants, which are assumed to act simultaneously for beams and frames.
- (3) Strain energy stored due to direct forces and in bending etc. is calculated and is partially differentiated with respect to the redundants.
- (4) A set of linear equations is obtained, the number of which is equal to that of the redundants. Solution of these equations evaluates the redundants.

#### NOTE:-

Special care must be exercised while partially differentiating the strain energy expressions and compatibility requirements of the chosen basic determinate structure should also be kept in mind. For the convenience of readers, Castigliano's theorem are given below:

#### 2.1. CASTIGLIANO'S FIRST THEOREM:-

"The partial derivative of the total strain energy stored with respect to a particular deformation gives the corresponding force acting at that point."

Mathematically this theorem is stated as below:

$$\frac{\partial \mathbf{U}}{\partial \Delta} = \mathbf{P}$$
$$\partial \mathbf{U}$$

 $\frac{\partial}{\partial \theta} = \mathbf{M}$ It suggests that displacements correspond to loads while rotations correspond to moments.

2.2. CASTIGLIANO'S SECOND THEOREM :-

"The partial derivative of the total strain energy stored with respect to a particular force gives the corresponding deformation at that point."

Mathematically,

$$\frac{\partial U}{\partial P} = \Delta$$

and

and

$$\frac{\partial U}{\partial M} = \theta$$

## 2.3. STATEMENT OF THEOREM OF LEAST WORK.

"In a statically indeterminate structure, the redundants are such that the internal strain energy stored is minimum." This minima is achieved by partially differentiating strain energy and setting it to zero or to a known value. This forms the basis of structural stability and of Finite Element Method.

## 2.4. Example No.1: <u>1st Degree Indeterminacy of Beams.</u>

Analyze the following loaded beam by the method of least work.



The beam is redundant to first degree.

In case of cantilever, always take free end as the origin for establishing moment expressions. Choosing cantilever with support at A and Rb as redundant. Apply loads and redundant simultaneously to BDS.



Taking B as origin (for variation of X)

$$\begin{split} M_X &= \left( RbX - \frac{wX^2}{2} \right) & 0 < X < L \\ U &= \frac{1}{2EI} \int_{0}^{L} M^2 \, dX. & \text{A generalized strain energy expression due to moments.} \end{split}$$

Therefore, partially differentiating the strain energy stored w.r.t. redundant, the generalized form is:

$$\frac{\partial U}{\partial R} = \frac{1}{EI} \int_{0}^{L} M\left(\frac{\partial M}{\partial R}\right) dX$$

Where R is a typical redundant.

Putting moment expression alongwith its limits of validity in strain energy expression.

$$U = \frac{1}{2EI} \int_{0}^{L} \left( RbX - \frac{wX^{2}}{2} \right)^{2} dX$$

Partially differentiate strain energy U w.r.t. redundant Rb, and set equal to zero.

So 
$$\frac{\partial U}{\partial Rb} = \Delta b = 0 = \frac{1}{EI} \int_{0}^{L} \left( RbX - \frac{wX^2}{2} \right) (X) dX$$
, because at B, there should be no deflection

$$0 = \frac{1}{\mathrm{EI}} \int_{0}^{L} \left[ \mathrm{RbX}^{2} - \frac{\mathrm{wX}^{3}}{2} \right] \mathrm{dX}$$
$$0 = \frac{1}{\mathrm{EI}} \left[ \frac{\mathrm{RbX}^{3}}{3} - \frac{\mathrm{wX}^{4}}{8} \right]_{0}^{L}$$
Or
$$\frac{\mathrm{RbL}^{3}}{3} = \frac{\mathrm{wL}^{4}}{8}$$
and
$$\boxed{\mathrm{Rb} = \frac{+3}{8} \mathrm{wL}}$$

The (+ve) sign with Rb indicates that the assumed direction of redundant Rb is correct. Now calculate Ra.

$$\Sigma Fy = 0$$
  
Ra + Rb = wL  
Ra = wL - Rb  
= wL -  $\frac{3}{8}$  wL  
=  $\frac{8 \text{ wL} - 3 \text{ wL}}{8}$   
Ra =  $\frac{5}{8}$  wL

Put X = L and Rb =  $\frac{3}{8}$  wL in moment expression for M<sub>X</sub> already established before to get Ma. Ma =  $\frac{3}{8}$  wL  $\cdot$ L  $-\frac{wL^2}{2}$ =  $\frac{3}{8}$  wL<sup>2</sup>  $-\frac{wL^2}{2}$ =  $\frac{3 wL^2 - 4 wL^2}{8}$ Ma =  $-\frac{wL^2}{8}$ 

The (-ve) sign with Ma indicates that this reactive moment should be applied such that it gives us tension at the top at point A.



**Example No.2:** Solve the following propped cantilever loaded at its centre as shown by method of least work.

BDS under loads and redundant. Taking point B as origin.

and

$$0 = \frac{\text{RbL}^{3}}{3} - \frac{5\text{PL}^{3}}{48}$$
  
Or 
$$\frac{\text{RbL}^{3}}{3} = \frac{5\text{PL}^{3}}{48}$$
  
Rb =  $\frac{+5\text{P}}{16}$ 

The (+ve) sign with Rb indicates that the assumed direction of redundant Rb is correct. Now Ra can be calculated.

$$\sum Fy = 0$$
  
Ra + Rb = P  
Ra = P - Rb  
Ra = P -  $\frac{5P}{16} = \frac{16P - 5P}{16}$   
Put X = L and Rb =  $\frac{5P}{16}$  in expression for Mac to get Ma  
Ma =  $\frac{5P}{16}$  L - P $\frac{L}{2}$   
=  $\frac{5 PL - 8 PL}{16}$   
Ma =  $\frac{-3 PL}{16}$ 

The (-ve) sign with Ma indicates that this reactive moment should be acting such that it gives us tension at the top.

# 2.5. 2<sup>ND</sup> DEGREE INDETERMINACY:-

**EXAMPLE NO. 3:** Analyze the following fixed ended beam loaded by Udl by least work method.



B.D.S. is chosen as a cantilever supported at A. Rb and Mb are chosen as redundants.



BDS UNDER LOADS AND REDUNDANTS

$$Mx = RbX - \frac{wX^2}{2} - Mb$$

0 < X < L

Choosing B as origin.

Write strain energy expression.

$$U = \frac{1}{2EI} \int_{0}^{L} \left[ RbX - \frac{wX^{2}}{2} - Mb \right]^{2} dX$$

Differentiate strain energy partially w.r.t. redundant Rb and use castigations theorem alongwith boundary condition.

$$\frac{\partial U}{\partial Rb} = \Delta b = 0 = \frac{1}{EI} \int_{0}^{L} \left[ RbX - \frac{wX^{2}}{2} - Mb \right] [X] dX$$

$$0 \qquad = \frac{1}{\mathrm{EI}} \int_{0}^{\mathrm{L}} \left[ \mathrm{Rb}X - \frac{\mathrm{w}X^{2}}{2} - \mathrm{Mb} \right] \mathrm{d}X$$

$$0 \qquad = \frac{1}{\mathrm{EI}} \left[ \mathrm{Rb} \, \frac{\mathrm{X}^3}{3} - \frac{\mathrm{w}\mathrm{X}^4}{8} - \frac{\mathrm{Mb}\mathrm{X}^2}{2} \right]_{\mathrm{o}}^{\mathrm{L}}$$

$$0 = \frac{1}{EI} \left[ Rb \frac{L^3}{3} - \frac{wL^4}{8} - \frac{MbL^2}{2} \right]$$
  
$$0 = Rb \frac{L^3}{3} - \frac{wL^4}{8} - \frac{MbL^2}{2}$$

As there are two redundants, so we require two equations. Now differentiate strain energy expression w.r.t. another redundants Mb. Use castigations theorem and boundary condition.

$$\frac{\partial U}{\partial Mb} = \theta b = 0 = \frac{1}{EI} \int_{0}^{L} \left[ RbX - \frac{wX^2}{2} - Mb \right] (-1) dX$$

$$0 = \frac{1}{EI} \int_{0}^{L} \left( -RbX + \frac{wX^2}{2} + Mb \right) dX$$

$$0 = \frac{1}{EI} \left[ -\frac{RbX^2}{2} + \frac{wX^3}{6} + MbX \right]_{0}^{L}$$

$$0 = -\frac{RbL^2}{2} + \frac{wL^3}{6} + MbL.$$

$$\frac{RbL^2}{2} - \frac{wL^3}{6} = MbL$$

$$Mb = \frac{RbL}{2} - \frac{wL^2}{6} \longrightarrow (2) \text{ Put Mb in equ}$$

So

uation 1, we get

 $\rightarrow$  (1)

$$0 = \frac{RbL^{3}}{3} - \frac{wL^{4}}{8} - \left(\frac{RbL}{2} - \frac{wL^{2}}{6}\right)\frac{L^{2}}{2}$$

$$0 = \frac{RbL^3}{3} - \frac{wL^4}{8} - \frac{RbL^3}{4} + \frac{wL^4}{12}$$
$$0 = \frac{RbL^3}{12} - \frac{wL^4}{24}$$
$$Rb = \frac{wL}{2}$$

Put Rb value in equation 2, we have  $Mb = \left(\frac{wL}{2}\right)\frac{L}{2} - \frac{wL^2}{6}$   $Mb = \frac{+wL^2}{12}$ 

The (+ve) value with Rb and Mb indicates that the assumed directions of these two redundants are correct. Now find other reactions Ra and Mb by using equations of static equilibrium.

Ra =  $\frac{wL}{2}$ 

$$\sum Fy = 0$$
  
Ra + Rb = wL  
Ra = wL - Rb  
= wL -  $\frac{wL}{2}$ 

Put X = L, Rb =  $\frac{wL}{2}$  & Mb =  $\frac{wL^2}{12}$  in M<sub>X</sub> expression to get Ma

$$Ma = \frac{wL}{2} \cdot L - \frac{wL^2}{2} - \frac{wL^2}{12}$$

$$Ma = -\frac{wL^2}{12}$$

The (-ve) sign with Ma indicates that this moment should be applied in such direction that it gives us tension at the top.

**Example No. 4:** Solve the same previous fixed ended beam by taking a simple beam as B.D.S.:-Choosing Ma and Mb as redundants.



B.D.S. is a simply supported beam, So Ma and Mb are redundants.

$$\begin{split} & \sum Ma = 0 \\ & Rb \times L + Ma = Mb + \frac{wL^2}{2} \\ & Rb \times L = (Mb - Ma) + \frac{wL^2}{2} \\ & Rb = \left(\frac{Mb - Ma}{L}\right) + \frac{wL}{2} \\ & Rb = \left(\frac{Mb - Ma}{L}\right) + \frac{wL}{2} \\ & So taking B as origin. Write M_x expression. \\ & M_x = RbX - Mb - \frac{wX^2}{2} \\ & 0 < X < L \\ \end{split}$$

$$\begin{aligned} & M_x = \left[\left(\frac{Mb - Ma}{L}\right) + \frac{wL}{2}\right] X - \frac{wX^2}{2} - Mb \\ & 0 < X < L. \\ Set up strain energy \\ & expression. \\ U = \frac{1}{2EI} \int_{0}^{L} \left[\left\{\left(\frac{Mb - Ma}{L}\right) + \frac{wL}{2}\right\} X - \frac{wX^2}{2} - Mb\right]^2 dX. \\ & Differentiate w.r.t. Ma first. \\ & Use castigations theorem and boundary conditions. \\ & \frac{\partial U}{\partial Ma} = \theta a = 0 = \frac{1}{EI} \int_{0}^{L} \left[\left\{\left(\frac{Mb - Ma}{L}\right) + \frac{wL}{2}\right\} X - \frac{wX^2}{2} - Mb\right] \left(-\frac{X}{L}\right) dX. \\ & D = \frac{1}{EI} \int_{0}^{L} \left(\frac{MbX}{L} - \frac{MaX}{L} + \frac{wL}{2} X - \frac{wX^2}{2} - Mb\right) \left(-\frac{X}{L}\right) dX. \\ & 0 = \frac{1}{EI} \int_{0}^{L} \left[-\frac{MbX^2}{L^2} + \frac{MaX^2}{L^2} - \frac{wX^2}{2} + \frac{MbX}{L}\right] dX \\ & 0 = \frac{1}{EI} \left[-\frac{Mb}{L^2} \frac{X^2}{3} + \frac{Ma}{L^2} \frac{X^3}{3} - \frac{wX^3}{6} + \frac{wX^4}{8L} + \frac{MbX^2}{2L}\right]_{0}^{L} \\ & Simplify it. \\ & 0 = \frac{MbL}{6} + \frac{MaL}{3} - \frac{wL^3}{24} \\ & \rightarrow (1) \end{aligned}$$

Now differentiate U Partially w.r.t. Mb. Use castiglianos theorem and boundary conditions.

$$\frac{\partial U}{\partial Mb} = \theta b = 0 = \frac{1}{EI} \int_{0}^{L} \left[ \left\{ \left( \frac{Mb - Ma}{L} \right) + \frac{wL}{2} \right\} X - \frac{wX^2}{2} - Mb \right] \left( \frac{X}{L} - 1 \right) dX$$
$$0 = \frac{1}{EI} \int_{0}^{L} \left( \frac{MbX}{L} - \frac{MaX}{L} + \frac{wL}{2} X - \frac{wX^2}{2} - Mb \right) \left( \frac{X}{L} - 1 \right) dX$$
$$0 = \int_{0}^{L} \left[ \frac{MbX^2}{L^2} - \frac{MaX^2}{L^2} + \frac{wLX^2}{2L} - \frac{wX^3}{2L} - \frac{MbX}{L} - \frac{MbX}{L} + \frac{MaX}{L} - \frac{wLX}{2} + \frac{wX^2}{2} + Mb \right] dX$$

$$0 = \left[\frac{MbX^3}{3L^2} - \frac{MaX^3}{3L^2} + \frac{wX^4}{6} - \frac{wX^4}{8L} - \frac{MbX^2}{2L} - \frac{MbX^2}{2L} + \frac{MaX^2}{2L} - \frac{wLX^2}{4} + \frac{wX^3}{6} + MbX\right]_0^L$$
Put limits now.  

$$0 = \left[\frac{MbL^3}{3L^2} - \frac{MaL^3}{3L^2} + \frac{wL^3}{6} - \frac{wL^4}{8L} - \frac{MbL^2}{2L} - \frac{MbL^2}{2L} + \frac{MaL^2}{2L} - \frac{wLX^2}{4} + \frac{wL^3}{6} + MbL\right]$$
Simplifying we get.  

$$0 = \frac{MbL}{3} + \frac{MaL}{6} - \frac{wL^3}{24}$$
or  $\frac{MbL}{3} = -\frac{MaL}{6} + \frac{wL^3}{24}$ 
So  $Mb = \frac{wL^2}{6} - \frac{Ma}{2} \right] \frac{L}{6} + \frac{MaL}{24}$  (2), Put Mb in equation (1) we get.  

$$0 = \left(\frac{wL^2}{8} - \frac{Ma}{2}\right) \frac{L}{6} + \frac{MaL}{24} - \frac{wL^3}{24}$$
Simplify to get Ma.  

$$0 = \frac{wL^3}{48} - \frac{MaL}{12} + \frac{MaL}{3} - \frac{wL^3}{24}$$
Simplify to get Ma.  

$$0 = \frac{wL^3}{48} - \frac{MaL}{12} + \frac{MaL}{3} - \frac{wL^3}{24}$$
Put Ma in equation (2), we have  
 $Mb = \frac{wL^2}{8} - \frac{wL^2}{12} \times \frac{1}{2}$ 
or  $Mb = \frac{wL^2}{12}$ ; Now Rb =  $\left(\frac{Ma + Mb}{L}\right) + \frac{wL}{2}$  Putting Ma and Mb we have.  
 $Rb = \frac{\left(\frac{wL^2}{12} - \frac{wL^2}{12}\right)}{L} + \frac{wL}{2}$ 
 $Rb = \frac{wL}{2}$ , Calculate Ra now.  
 $\sum Fy = 0$   
 $Ra + Rb = wL$   
 $Ra = wL - Rb$   
 $Ra = wL - Rb$   
 $Ra = wL - \frac{wL}{2}$ 

We get same results even with a different BDS. The beam is now statically determinate. SFD and BMD can be drawn. Deflections at can be found by routine methods.

# 2.6. 2<sup>ND</sup> DEGREE INDETERMINACY OF BEAMS:-

Exmaple No. 5: Solve the following loaded beam by the method of least work.



B.D.S. is a cantilever supported at A. Rb & Rc are chosen as redundants.



Choosing C as origin, Set-up moment expressions in different parts of this beam.

$$Mbc = Rc.X - \frac{wX^2}{2} \qquad \qquad 0 < X < \frac{L}{2}$$

Mab = Rc.X + Rb $\left(X - \frac{L}{2}\right) - \frac{wX^2}{2}$   $\frac{L}{2} < X < L$ . Write strain energy expression for entire structure.

$$U = \frac{1}{2EI} \int_{0}^{L/2} \left[ Rc.X - \frac{wX^{2}}{2} \right]^{2} dX + \frac{1}{2EI} \int_{L/2}^{L} \left[ Rc.X + Rb\left(X - \frac{L}{2}\right) - \frac{wX^{2}}{2} \right]^{2} dX$$

Partially differentiate it w.r.t. redundant Rc first. Use castiglianos theorem and boundary conditions.

$$\frac{\partial U}{\partial Rc} = \Delta c = 0 = \frac{1}{EI} \int_{0}^{L/2} \left[ Rc.X - \frac{wX^2}{2} \right] [X] dX + \frac{1}{EI} \int_{L/2}^{L} \left[ Rc.X + Rb\left(X - \frac{L}{2}\right) - \frac{wX^2}{2} \right] [X] dX$$

$$0 = \frac{1}{EI} \int_{0}^{L/2} \left[ Rc.X^2 - \frac{wX^3}{2} \right] dX + \frac{1}{EI} \int_{L/2}^{L} \left[ Rc.X^2 + Rb.X^2 - \frac{Rb.LX}{2} - \frac{wX^3}{2} \right] dX$$
Integrate it.
$$0 = \frac{1}{EI} \left[ Rc.\frac{X^3}{3} - \frac{wX^4}{8} \right]_{0}^{L/2} + \frac{1}{EI} \left[ Rc.\frac{X^3}{3} + Rb.\frac{X^3}{3} - \frac{RbLX^2}{4} - \frac{wX^4}{8} \right]_{L/2}^{L}$$
Insert limits and simplify.

$$0 = \frac{\text{Rc.L}^3}{3} + \frac{5\text{Rb.L}^3}{48} - \frac{\text{wL}^4}{8} \longrightarrow (1)$$

Now partially differentiate strain energy w.r.t. Rb. Use Castiglianos theorem and boundary conditions.

$$\begin{aligned} \frac{\partial U}{\partial Rb} &= \Delta b = 0 = \frac{1}{EI} \int_{0}^{L/2} \left[ Rc.X - \frac{wX^2}{2} \right] (0) dX + \frac{1}{EI} \int_{L/2}^{L} \left[ Rc.X + Rb\left(X - \frac{L}{2}\right) - \frac{wX^2}{2} \right] \left[ X - \frac{L}{2} \right] dX \\ 0 &= 0 + \frac{1}{EI} \int_{L/2}^{L} \left[ Rc.X^2 + RbX^2 - \frac{RbLX}{2} - \frac{wX^3}{2} - \frac{Rc.L.X}{2} - \frac{RbL.X}{2} - \frac{RbL.X}{2} + \frac{Rb.L^2}{4} + \frac{wL.X^2}{4} \right] dX. \\ Integrate. \\ 0 &= \frac{1}{EI} \left[ \frac{Rc.X^3}{3} + \frac{Rb.X^3}{3} - \frac{Rb.L.X^2}{4} - \frac{wX^4}{8} - \frac{Rc.L.X^2}{4} - \frac{Rb.LX^2}{4} - \frac{Rb.LX^2}{4} + \frac{Rb.L^2.X}{4} + \frac{wL.X^3}{12} \right]_{L/2}^{L}. \\ Put limits \\ 0 &= \frac{Rc.L^3}{3} + \frac{Rb.L^3}{3} - \frac{Rb.L^3}{4} - \frac{wL^4}{8} - \frac{Rc.L^3}{4} - \frac{Rb.L^3}{4} + \frac{Rb.L^3}{4} + \frac{wL^4}{12} - \frac{Rc.L^3}{24} - \frac{Rb.L^3}{24} \\ &+ \frac{Rb.L^3}{16} + \frac{wL^4}{128} + \frac{Rc.L^3}{16} - \frac{Rb.L^3}{8} - \frac{wL^4}{96} \end{aligned}$$

Simplify to get Rc. =  $-\frac{2}{5}$  Rb.  $+\frac{17}{40}$  wL  $\rightarrow$  (2) Put this value of Rc in equation (1), to get Rb

$$0 = \left(-\frac{2}{5} \operatorname{Rb.} + \frac{17}{40} \operatorname{wL}\right) \frac{\mathrm{L}^3}{3} + \frac{5}{48} \operatorname{Rb.L}^3 - \frac{\operatorname{wL}^4}{8}$$
(1)

$$0 = -\frac{2}{15} \operatorname{Rb.L}^3 + \frac{17}{120} \operatorname{wL}^4 + \frac{5}{48} \operatorname{Rb.L}^3 - \frac{\operatorname{wL}^4}{8}$$

Simplify to get

Rb. = 
$$\frac{12}{21}$$
 wL

Put value of Rb in equation (2) and evaluate Rc,

$$Rc = -\frac{2}{5} \times \frac{12}{21} WL + \frac{17}{40} WL$$
$$Rc = \frac{11}{56} WL$$

The (+ve) signs with Rb & Rc indicate that the assumed directions of these two redundants are correct. Now calculate Ra.

$$\sum Fy = 0$$

$$Ra + Rb + Rc = wL$$

Ra = wL - Rb - Rc. Put values of Rb and Rc from above and simplify. or

$$= wL - \frac{12}{21}wL - \frac{11 wL}{56}$$
  
Ra =  $\frac{373}{1176}wL$   
Ra =  $\frac{91}{392}wL$ 

Putting the values of these reactions in Mx expression for span AB and set X = L, we have

Ma = Rc.L + Rb.  $\frac{L}{2} - \frac{wL^2}{2}$ . Put values of Rb and Rc from above and simplify.

$$= \frac{11 \text{ wL}}{56} \text{ L} + \frac{12}{21} \text{ wL} \times \frac{\text{L}}{2} - \frac{\text{wL}^2}{2}$$

$$Ma = -\frac{21}{1176} \text{ wL}^2$$

$$Ma = -\frac{7}{392} \text{ wL}^2$$

The (-ve) sign with Ma indicates that this reactive moment should be applied in such a direction that gives us tension at the top. Now the beam has been analyzed and it is statically determinate now.

## 2.7. INTERNAL INDETERMINACY OF STRUCTURES BY FORCE METHOD :-

The question of internal indeterminacy relates to the skeletal structures like trusses which have discrete line members connected at the ends. The structures which fall in this category may include trusses and skeletal frames.

For fixed ended portal frames, the question of internal indeterminacy is of theoretical interest only.



Consider he truss shown in the above diagram. If this truss is to be treated as internally indeterminate, more than one members can be considered as redundants. However, the following points should be considered for deciding the redundant members.

(1) The member which is chosen the redundant member is usually assumed to be removed or cut. The selection of redundant should be such that it should not effect the stability of the remaining structure.

- (2) The skeletal redundant members will have unequal elongations at the two ends and in the direction in which the member is located. For example, if a horizontal member is chosen as redundant, then we will be concerned with the relative displacement of that member in the horizontal direction only.
- (3) Unequal nodal deflection  $(\Delta_1 \Delta_2)$  of a typical member shown above which is often termed as relative displacement is responsible for the self elongation of the member and hence the internal force in that member.

## 2.7.1. FIRST APPROACH: WHEN THE MEMBER IS REMOVED :-

With reference to the above diagram, we assume that the redundant member (sloping up to left) in the actual structure is in tension due to the combined effect of the applied loads and the redundant itself. Then the member is removed and now the structure will be under the action of applied loads only.



Due to the applied loads, the distance between the points B and D will increase. Let us assume that point B is displaced to its position  $B_2$ . This displacement is termed as  $\Delta$  apart. Now the same structure is considered under the action of redundant force only and let us assume that point  $B_2$  comes to its position  $B_1$  (some of the deflections have been recovered). This displacement is termed as  $\Delta$  together. The difference of these two displacements ( $\Delta$ apart –  $\Delta$ together) is infact the self lengthening of the member BD and the compatibility equation is

 $\Delta$ apart –  $\Delta$ together = self elongation.

## 2.7.2. 2ND APPROACH

We assume that the member is infact cut and the distance between the cut ends has to vanish away when the structure is under the action of applied loads and the redundant. In other words, we can say that the deformation produced by the applied loads plus the deformation produced by the redundant should be equal to zero.



 $\label{eq:constraint} Total \qquad Deflection produced by redundants \ \Delta \times R = \sum_{i=1}^{n} \quad \frac{2}{\underline{U}_{i}\underline{Li}} \times X$ 

Total Deflection produced by loads  $\Delta \times L = \sum_{i=1}^{n} \frac{FiUiLi}{AiEi}$ 

If deflection is (+ve), there is elongation. If deflection is (-ve), there is shortening. Now  $U = \frac{P^2L}{2AE}$  Elastic strain energy stored due to axial forces



## PROOF:-

Work done =  $1/2 P.\Delta$  = shaded area of P –  $\Delta$  diagram. Now f  $\alpha \in$  (Hooke's Law)

or 
$$\frac{P}{A} \alpha \frac{\Delta}{L}$$
 (For direct stresses)  
 $\frac{P}{A} = E \frac{\Delta}{L}$  where E is Yung's Modulus of elasticity.  
 $\Delta = \frac{PL}{AE}$ 

Therefore work done  $= \frac{P\Delta}{2} = \frac{1}{2}P. \frac{PL}{AE}$  (Shaded area under P- $\Delta$  line – By putting value of  $\Delta$ )

Work done 
$$= \frac{P^2 L}{2AE}$$
 (for single member)

Work done = 
$$\sum \frac{P^2 L}{2AE}$$
 (for several members)

We know that Work done is always equal to strain energy stored.

## **EXAMPLE NO 6:**

#### Analyze the truss shown below by Method of Least work. Take

- (1) Member  $U_1L_2$  as redundant.
- (2) Member  $U_1U_2$  as redundant. Number in brackets () are areas  $\times 10^{-3}$  m<sup>2</sup>. E = 200  $\times 10^{6}$  KN/m<sup>2</sup>



Note: In case of internally redundant trusses, Unit load method (a special case of strain energy method) is preferred over direct strain energy computations followed by their partial differentiation.
 SOLUTION: Case 1 – Member U<sub>1</sub>L<sub>2</sub> as redundant



F-Diagram

- (1)  $U_1L_2$  is redundant.: STEPS
  - 1 Remove this member. (See diagram)
  - 2 Assume that tensile forces would be induced in this member.
  - 3 Analyze the structure without  $U_1L_2$  (B.D.S.) or F' diagram.
  - 4 Displacement of members due to redundant + that due to loads should be equal to zero. OR

 $\Delta \times L \ + \ \Delta \times R = \ 0$ 

5 – Analyze the truss with unit tensile force representing  $U_1L_2$  or U-diagram.



We shall determine member forces for F' - diagram by method of moments and shears as explained earlier. These are shown in table given in pages to follow. Member forces in U-diagram are determined by the method of joints.



JOINT (L<sub>2</sub>)

Joint (L1)



 $\sum F_X = 0$ 

 $L_{1}U_{2} \sin\theta - 0.6 = 0$   $L_{1}U_{2} = \frac{0.6}{0.6} = +1$   $\sum Fy = 0$   $L_{1}U_{2} \times 0.80 + UL_{1} = 0 \implies U_{1}L_{1} = -0.80$ 

Now Book F' forces induced in members as determined by moments and shears method and U forces as determined by method of joints in a tabular form.

Member	$A \times 10^{-3}$				F'UL	$\frac{\mathrm{U}^{2}\mathrm{L}}{\mathrm{U}^{-3}}$	Fi=Fi'
		L	Fi'	Ui	$\overline{AE} \times 10^{5}$	$\overline{AE} \times 10^{-1}$	+UiX
	(m <sup>2</sup> )	(m)	(KN)		(m)	(m)	(KN)
$U_1U_2$	2.4	4.5	- 12	-0.6	+0.0675	3.375×10 <sup>-3</sup>	- 25.15
LoL <sub>1</sub>	2.4	4.5	+12	0	0	0	+12
$L_1L_2$	2.4	4.5	+24	-0.6	- 0.135	3.375×10 <sup>-3</sup>	+10.84
$L_2L_3$	2.4	4.5	+24	0	0	0	+24
LoU <sub>1</sub>	3.0	7.5	- 20	0	0	0	- 20
$L_1U_2$	4.8	7.5	- 20	+1.0	- 0.416	20.83×10 <sup>-3</sup>	+ 1.93
$U_2L_3$	3.0	7.5	- 40	0	0	0	- 40
$U_1L_1$	1.2	6.0	+16	-0.8	- 0.32	16×10 <sup>-3</sup>	- 1.54
$U_2L_2$	1.2	6.0	+48	-0.8	- 0.96	16×10 <sup>-3</sup>	+30.456
$U_1L_2$	1.8	7.5	0	+1.0	0	20.83×10 <sup>-3</sup>	+21.96

 $\begin{array}{ccc} \Sigma {-}1.7635 \times & \sum 80.91 & \times \\ 10^{-3} & 10^{-6} \end{array}$ 

Compatibility equation is  $\Delta \times L + \Delta \times R = 0$ 

$$\Delta \times \mathbf{L} + \Delta \times \mathbf{R} = 0$$
$$\Delta \times \mathbf{L} = \sum_{1}^{n} \frac{\mathbf{F}' \mathbf{U} \mathbf{L}}{\mathbf{A} \mathbf{E}}$$

 $\Delta \times \mathbf{R} = \sum_{1}^{n} \frac{\mathbf{U}^{2} \mathbf{L}}{\mathbf{A} \mathbf{E}} \cdot \mathbf{X}$ 

Putting values from above table in compatibility equation. Where R = X = force in redundant Member  $U_1L_2$ 

$$-1.7635 \times 10^{-3} + 80.41 \times 10^{-6} \cdot X = 0$$
  
or 
$$-1.7635 \times 10^{-3} + 0.08041 \times 10^{-3} \cdot X = 0$$
  
$$-1.7635 + 0.08041 \times X = 0$$
  
$$0.08041 X = 1.7635$$
  
$$X = \frac{1.7635}{0.08041}$$
  
$$X = + 21.93 \text{ KN} \qquad \text{(Force in members U}_1\text{L}_2\text{)}$$

Now final member forces will be obtained by formula Fi = Fi' + Ui X. These are also given in above table. Apply check on calculated forces.

## **Check on forces** Joint Lo



Tensile forces in above table carry positive sign and are represented as acting away from joint. Note: Compressive forces carry negative sign and are represented in diagram as acting towards the joint.  $\Sigma F x = 0$ 

$$2 Fx = 0$$

$$12 - 20 Sin \theta = 0$$

$$12 - 20 \times 0.6 = 0$$

$$0 = 0$$

$$\sum Fy = 0$$

$$16 - 20 Cos \theta = 0$$

$$16 - 20 \times 0.8 = 0$$

$$0 = 0$$

Checks have been satisfied showing correctness of solution.

## **EXMAPLE NO. 7:**

CASE 2: Analyze previous loaded Truss by taking U1 U2 as Redundant



In this case member forces in BDS (F' diagram) have been computed by method of joints due to obvious reasons.)

Joint Lo:-





 $\sum Fy = 0$  $L_1U_2 \cos\theta + 32 = 0$ 

$$L_{1}U_{2} = -\frac{32}{0.8}$$

$$L_{1}U_{2} = -40$$

$$\sum FX = 0$$

$$L_{1}L_{2} + L_{1}U_{2} \sin\theta - 12 = 0$$

$$L_{1}L_{2} - 40 \times 0.6 - 12 = 0$$

$$L_{1}L_{2} = 36$$

Joint U<sub>2</sub>



$$\sum FX = 0$$
  

$$40 \sin\theta + U_2L_3 \sin\theta = 0$$
  

$$40 \times 0.6 + U_2L_3 \times 0.6 = 0$$
  

$$U_2L_3 = -40$$
  

$$\sum Fy = 0$$
  

$$40 \cos\theta - U_2L_3 \cos\theta - U_2L_2 = 0$$
  

$$40 \times 0.8 - (-40) \times 0.8 - U_2L_2 = 0$$
  

$$U_2L_2 = 64$$

Joint L<sub>2</sub>



$$\begin{split} & \sum FX \; = \; 0 \\ & L_2 L_3 + 20 \; Sin\theta - 36 \; = \; 0 \\ & L_2 L_3 + 20 \times 0.6 - 36 \; = \; 0 \\ & L_2 L_3 - 24 \; = \; 0 \\ & L_2 L_3 \; = \; 24 \end{split}$$

Joint L<sub>3</sub> (Checks)



0 = 0 Checks are satisfied. Results are OK and are given in table at page to follow: Now determine member forces in U diagram.



U-Diagram (BDS under unit redundant force)

Joint U<sub>1</sub>



$$\begin{split} & \sum FX = 0 \\ & 1 + U_1L_2 \times Sin\theta = 0 \\ & 1 + U_1L_2 \times 0.6 = 0 \end{split}$$

Joint L<sub>1</sub> :-



Entering results of member forces pertaining to  $F^\prime$  diagram and U diagram alongwith member properties in a tabular form.

Mem-	$A \times$	L	Fi'	$U_1$	F'UL 10 <sup>-3</sup>	$\frac{\mathrm{U}^{2}\mathrm{L}}{\mathrm{U}^{-3}}$	Fi=Fi+UiX
ber	$10^{-3}$	(m)	(KN)		$\overline{AE} \times 10^{-1}$	AE × 10	(KN)
	(m)				(m)	(m)	
$U_1U_2$	2.4	4.5	0	+1	0	$9.375 \times 10^{-3}$	-25.34
LoL <sub>1</sub>	2.4	4.5	+12	0	0	0	+ 12
$L_1L_2$	2.4	4.5	+ 36	+ 1	+0.3375	$9.375 \times 10^{-3}$	+10.66
$L_2L_3$	2.4	4.5	+24	0	0	0	+ 24
LoU <sub>1</sub>	3.0	7.5	- 20	0	0	0	- 20
$L_1U_2$	1.8	7.5	- 40	-1.66	+1.383	$57.4 \times 10^{-3}$	+2.06
$U_2L_3$	3.0	7.5	- 40	0	0	0	- 40
$U_1L_1$	1.2	6.0	+ 32	1.328	1.0624	$44.09 \times 10^{-3}$	+ 65.65
$U_2L_2$	1.2	6.0	+ 64	1.328	2.1248	$44.09 \times 10^{-3}$	+ 97.65
$U_1L_2$	1.8	7.5	- 20	-1.66	0.691	$57.4 \times 10^{-3}$	- 62.06
					$\Sigma 5.6 \times 10^{-3}$	$\sum 221.73 \times 10^{-6}$	

## Compatibility equation is

 $\Delta \times L + \Delta \times R = 0$  Putting values of  $\Delta \times L$  and  $\Delta \times R$  due to redundant from above table.  $56 \times 10^{-3} + 221.73 \times 10^{-6} \text{ X} = 0$ , where X is force in redundant member  $U_1U_2$ .

or 
$$5.6 \times 10^{-3} + 0.22173 \times 10^{-3} \text{ X} = 0$$

$$X = \frac{5.6 \times 10^{-3}}{0.22173 \times 10^{-3}}$$

X = -25.34 KN. Therefore forces in truss finally are as follows. (by using formula (Fi = Fi' + UiX and are given in the last column of above table)

$$FU_1\,U_2=0+Ui.x=0-25.34\times 1=-\,25.34$$

$$FLoL_{1} = 12 - 25.34 \times 0 = + 12$$
  

$$FL_{1}L_{2} = 36 - 25.34 \times 1 = + 10.66$$
  

$$FL_{2}L_{3} = 24 - 0 = + 24$$
  

$$FLoU_{1} = -20 - 0 \times 25.34 = -20$$
  

$$FL_{1}U_{2} = -40 + 1.66 \times 25.34 = + 2.06$$
  

$$FU_{2}L_{3} = -40 + 0 \times 25.34 = -40$$
  

$$FU_{1}L_{1} = + 32 + 1.328 \times 25.34 = + 65.65$$
  

$$FU_{2}L_{2} = + 64 + 1.328 \times 25.34 = + 97.65$$

 $FU_1L_2 = -20 - 1.66 \times 25.34 = -62.06$ . Now based on these values final check can be applied.

Joint Lo.



## 2.8. STEPS FOR TRUSS SOLUTION BY METHOD OF LEAST WORK.

Now instead of Unit load method, we shall solve the previous truss by direct use of method of least work.

- (1) Consider the given truss under the action of applied loads and redundant force X in member  $U_1L_2$
- (2) The forces in the relevant rectangle will be a function of applied load and redundant force X. (As was seen in previous unit load method solution)
- (3) Formulate the total strain energy expression due to direct forces for all the members in the truss.
- (4) Partially differentiate the above expressions with respect to X.
- (5) Sum up these expressions and set equal to zero. Solve for X.
- (6) With this value of X, find the member forces due to applied loads and redundant acting simultaneously (by applying the principle of super positions).

## EXAMPLE NO. 8 :-

Analyze the loaded truss shown below by least work by treating member  $U_1L_2$  as redundant. Numbers in ( ) are areas  $\times 10^{-3}$  m<sup>2</sup>. E =  $200 \times 10^6$  KN/m<sup>2</sup>.

## SOLUTION:-



Stable Indeterminate to 1st degree.



F - Diagram (Truss under loads and redundant)

**NOTE:** Only the rectangle of members containing redundant X contains forces in terms of X as has been seen earlier. Now analyze the Truss by method of joints to get Fi forces.

JOINT L0

$$\sum Fy = 0$$

$$LoU_1 Cos\theta + 16 = 0$$

$$LoU_1 Cos\theta + 16 = 0$$

$$LoU_1 = \frac{-16}{Cos\theta}$$

$$= \frac{-16}{0.8}$$

$$\sum FX = 0$$

$$LoL_1 + LoU_1 Sin\theta = 0$$

$$LoL_1 + (-20) \times 0.6 = 0$$

$$LoL_1 - 12 = 0$$

$$IoL_1 - 12 = 0$$

$$IoL_1 = 12 KN$$
Joint U<sub>1</sub>

$$\sum FX = 0$$

$$U_1 U_2 + X Sin\theta + 20 Sin\theta = 0$$

 $U_1\,U_2 + X \times 0.6 + 20 \times 0.6 = 0$ 

$$\begin{split} & \boxed{U_1 \, U_2 = - \left(0.6 \; X + 12\right)} \\ \Sigma \; Fy \; = \; 0 \\ & - \, U_1 \, L_1 - X \; Cos\theta + 20 \; Cos\theta = 0 \\ & - \, U_1 \, L_1 - X \times 0.8 + 20 \times 0.8 \; = 0 \\ & U_1 \, L_1 \; = \; - \; 0.8 \; X + 16 \\ \hline & \boxed{U_1 L_1 = - \left(0.8 \; X - 16\right)} \end{split}$$

Joint L<sub>1</sub> :-



$$\begin{split} & \sum Fy \; = \; 0 \\ & - \; (0.8X - 16) + L_1 \, U_2 \, Cos\theta = 0 \\ & L_1 U_2 \; \times \; 0.8 = 0.8 \; X - 16 \end{split}$$

$$L_1U_2 = (X - 20)$$

$$\begin{split} & \sum FX \; = \; 0 \\ & L_1L_2 + L1U2\; Sin\theta - 12 = 0 \\ & L_1L_2 + (X-20\;) \times 0.6 - 12 = 0 \\ & L_1L_2 + 0.6\; X - 12 - 12 \; = 0 \end{split} \label{eq:L1}$$

$$L_1 L_2 = -(0.6X - 24)$$

Joint  $U_2$ 



$$\sum FX = 0$$
  
(0.6 X + 12) + U<sub>2</sub>L<sub>3</sub> Sin $\theta$  - (X - 20) Sin $\theta$  = 0  
0.6 X + 12 + U<sub>2</sub>L<sub>3</sub> × 0.6 - (X - 20) × 0.6 = 0

10

0 (11 1

$$U_{2}L_{3} = \frac{-24}{0.6}$$

$$U_{2}L_{3} = -40 \text{ KN}$$

$$\Sigma \text{ Fy } = 0$$

$$-U_{2}L_{2} - (X - 20) \cos\theta - U_{2}L_{3} \cos\theta = 0$$

$$-U_{2}L_{2} - (X - 20) \times 0.8 - (-40) \times 0.8 = 0$$

$$-U_{2}L_{2} - 0.8 \text{ X} + 16 + 32 = 0$$

$$-0.8 \text{ X} + 48 = U_{2}L_{2}$$

0 6 17

10 0

$$U_2L_2 = -(0.8X - 48)$$

Joint L<sub>2</sub>:-



 $\sum FX = 0$   $L_{2}L_{3} + 0.6 X - 24 - X \sin\theta = 0$   $L_{2}L_{3} = -0.6 X + 24 + 0.6 X$  $\boxed{L_{2}L_{3} = 24 \text{ KN}}$ 

$$\sum Fy = 0$$
  
- (0.8X - 48) - 48 + X Cos $\theta$  = 0  
- 0.8X + 48 - 48 + 0.8X = 0  
0 = 0 (Check)

Joint L<sub>3</sub> :-

At this joint, all forces have already been calculated. Apply checks for corretness.



$$\sum FX = 0$$
40 Sin $\theta - 24 = 0$ 
40 × 0.6 - 24 = 0
24 - 24 = 0
0 = 0 O.K.
$$\sum Fy = 0$$
- 40 Cos $\theta$  + 32 = 0
- 40 × 0.8 + 32 = 0
- 32 + 32 = 0 O.K. Checks have been satisfied.
0 = 0

This means forces have been calculated correctly. We know that strain energy stored in entire Truss is  $U = \sum \frac{Fi^2L}{2AE}$ 

So, 
$$\frac{\partial U}{\partial X} = \Delta = 0 = \frac{\sum Fi \frac{\partial Fi}{\partial X} \cdot Li}{AE}$$
  
 $\frac{\sum Fi \frac{\partial Fi}{\partial X} \cdot Li}{AE} = 0 = 80.41 \times 10^{-6} \text{X} - 1764.17 \times 10^{-6}$  Values of Fi and Li for various

members have been picked up from table annexed.

$$0 = 80.41 \text{ X} - 1764.17$$

or 
$$80.41 \text{ X} = 1764.17$$
  
 $X = \frac{1764.17}{80.41}$   
 $X = 21.94 \text{ KN}$ 

Now putting this value of X in column S of annexed table will give us member forces.

Now apply equilibrium check on member forces calculated. You may select any Joint say  $L_1$ . Joint  $L_1$ :-



$$\begin{split} \sum FX &= 0, \\ 10.84 - 12 &+ 1.94 \text{ Sin}\theta = 0 \\ \text{or } 10.84 - 12 + 1.94 \times 0.6 = 0, \\ \text{r} & 0 &= 0 \text{ (Check)} \\ \end{split}$$

or

Insert here Page No. 138-A



 $\rightarrow$ 

EXAMPLE NO. 9:- By the force method analyze the truss shown in fig. below. By using the forces in members  $L_1U_2$  and  $L_2U_3$  as the redundants. Check the solution by using two different members as the redundants.  $E = 200 \times 10^{6} \text{ KN/m}^{2}$ 

Compatibility equations are:

$$\Delta X_1 L + \Delta X_1 R_1 + \Delta X_1 R_2 = 0$$

$$\Delta X_2 L + \Delta X_2 R_1 + \Delta X_2 R_2 = 0$$

Here

 $\begin{array}{rcl} R_1 &=& X_1 \\ R_2 &=& X_2 \end{array}$ 

(1) Change in length in member 1 due to loads and two redundants should be zero.

(2) Change in length in member 2 due to loads and two redundants should be zero.

Where  $\Delta X_1 L = \frac{\sum F' U_1 L}{AE}$  = Deflection produced in member (1) due to applied loads.  $\Delta X_1 R_1 = \text{Deflection produced in member (1) due to redundant } R_1 = \Sigma \left(\frac{U_1^2 L}{AE}\right)$ .  $X_1$  $\Delta x_1 R_2$  = Deflection produced in member (1) due to redundant  $R_2 = \Sigma \left(\frac{U_1 U_2 L}{AE}\right)$ .  $X_2$  $\Delta x_2 L$  = Deflection produced in member (2) due to loads =  $\sum \frac{F' U_2 L}{AF}$  $\Delta x_2 R_1$  = Deflection produced in member (2) due to redundant  $R_1 = \Sigma \left(\frac{U_1 U_2 L}{AE}\right)$ .  $X_1$  $\Delta x_2 R_2$  = Deflection produced in member (2) due to redundant  $R_2 = \Sigma \left(\frac{U_2^2 L}{AE}\right)$ .  $X_2$ 

From table attached, the above evaluated summations are picked up and final member forces can be seen in the same table. All member forces due to applied loads (Fi' diagram) have been determined by the method of moments and shears and by method of joints for  $U_1$  and  $U_2$  diagrams.

Evaluation of member forces in verticals of F' – Diagram :-

Forces in verticals are determined from mothod of joints for different trusses shown above.

(Joint  $L_1$ )



 $U_1L_1 = 48$ 

 $\sum Fy = 0$ 

(Joint U<sub>2</sub>)



 $\sum Fy = 0$  $-U_2L_2 + 52.5 \operatorname{Cos}\theta = 0$  $-U_2L_2 + 52.5 \times 0.8 = 0$  $U_2L_2=52.5\times0.8$ 

$$U_2L_2 = +42$$



Evaluation of forces in verticals of  $U_1$  – Diagram:-  $(Joint \; L_1)$ 



$$\sum Fy = 0$$
  
+ 0.8 - U<sub>1</sub>L<sub>2</sub>Cos  $\theta = 0$   
0.8 = U<sub>1</sub>L<sub>2</sub> × 0.8  
U<sub>1</sub>L<sub>2</sub> = 1  
so U<sub>1</sub>U<sub>2</sub> + 1 × 0.6 = 0 Putting value of U<sub>1</sub>L<sub>2</sub> in  $\sum FX$ .  
U<sub>1</sub>U<sub>2</sub> = -0.6

Now from the table, the following values are taken.

$$\begin{split} \Delta X_1 L &= -0.671 \times 10^{-3} \\ \Delta X_1 R_1 &= 125.7 \times 10^{-6} X1 = 0.1257 \times 10^{-3} X1 \\ \Delta X_1 R_2 &= 32 \times 10^{-6} X2 = 0.032 \times 10^{-3} X2 \\ \Delta X_2 L &= -6.77 \times 10^{-3} \\ \Delta X_2 R_1 &= 0.032 \times 10^{-3} X1 \\ \Delta X_2 R_2 &= 125.6 \times 10^{-6} X2 = 0.1256 \times 10^{-3} X2 \end{split}$$

Putting these in compatibility equations, we have.

$$-0.671 \times 10^{-3} + 0.1257 \times 10^{-3} \text{X1} + 0.032 \times 10^{-3} \text{X2} = 0 \qquad \rightarrow (1)$$

$$-6.77 \times 10^{-3} + 0.032 \times 10^{-3} \text{ X1} + 0.1256 \times 10^{-3} \text{ X2} = 0 \qquad \rightarrow (2)$$

dividing by  $10^{-3}$ 

$$-0.671+0.1257X1 + 0.032X2 = 0 \rightarrow (1)$$
  

$$-6.77 + 0.032X1 + 0.1256X2 = 0 \rightarrow (2)$$
  
From (1),  $X_1 = \frac{0.671 - 0.032X_2}{0.1257} \rightarrow (3)$ 

Put  $X_1$  in (2) & solve for  $X_2$ 

$$-6.77 + 0.032 \left[ \frac{0.671 - 0.032X_2}{0.1257} \right] + 0.1256X_2 = 0$$
  
$$-6.77 + 0.171 - 8.146 \times 10^{\circ}3X2 + 0.1256X_2 = 0$$
  
$$-6.599 + 0.1174X_2 = 0$$
  
$$0.1174X2 = 6.599$$
  
$$\boxed{X2 = 56.19 \text{ KN}}$$
  
$$\exp(3) \qquad X1 = \frac{0.671 - 0.032 \times 56.19}{0.0000}$$

From (3)  $X1 = \frac{0.071 - 0.032 \times 30.19}{0.1257}$ X1 = -8.96 KN

After redundants have been evaluated, final member forces can be calculated by using the formula shown in last column of table. Apply checks on these member forces.

CHECKS:-



The results are O.K. Follow same procedure if some other two members are considered redundant. See example No. 12.

Insert Page No. 143-A

## 2.9. SIMULTANEIOUS INTERNAL AND EXTERNAL TRUSS REDUNDANCY

**EXAMPLE NO. 10:** Determine all reactions and member forces of the following truss by using castiglianos theorem or method of least work. Consider it as:

- (i) internally redundant;
- (ii) internally and externally redundant.

Nos. in ( ) are areas in 
$$\times 10^{-3}$$
m<sup>2</sup>. E = 200  $\times 10^{6}$  KN/m<sup>2</sup>



## **SOLUTION:**

#### **DEGREE OF INDETERMINACY:-**

 $D = (m + r) - 2i = (10 + 4) - 2 \times 6 = 2$ 

Therefore, the truss is internally statically indeterminate to the 2nd degree. There can be two approaches, viz, considering two suitable members as redundants and secondly taking one member and one reaction as redundants for which the basic determinate structure can be obtained by cutting the diagonal CE and replacing it by a pair of forces  $X_1 - X_1$  and replacing the hinge at F by a roller support with a horizontal redundant reaction HF =  $X_2$ . Applying the first approach and treating inclineds of both storeys sloping down to right as redundants.

## (I) WHEN THE TRUSS IS CONSIDERED AS INTERNALLY REDUNDANT :-



Applying method of joints for calculating member forces.

Consider Joint (C) and all unknown forces are assumed to be in tension to begin with , acting away from the joint. Length AE= 10 m ,  $\cos \theta = 0.6$  ,  $\sin \theta = 0.8$ 



 $\begin{array}{l} -S_{AB} - X_{2} \sin\theta - (20 + 0.8 X_{1}) + (5+X_{1}) \sin\theta = 0 \\ -S_{AB} - 0.8 X_{2} - 20 - 0.8 X_{1} + 4 + 0.8 X_{1} = 0 \\ S_{AB} = -(16 + 0.8 X_{2}) \end{array}$ Joint (E)  $\begin{array}{c} (24 + 0.8 \times 1) \\ & & & \\ & \\ & & \\ &$ 

Enter Forces in table. Now applying Catiglianos' theorem and taking values from table attached.

$$\sum S \cdot \frac{\partial S}{\partial X_1} \cdot \frac{L}{AE} = 0 = 485.6 + 65.64X_1 + 2.7X_2 = 0$$
(1)

and

$$\Sigma S. \frac{\partial S}{\partial X_2} \cdot \frac{L}{AE} = 0 = 748.3 + 2.7X_1 + 62.94 X_2 = 0$$
(2)

or 
$$485.6 + 65.64 X_1 + 2.7 X_2 = 0 \rightarrow (1)$$
  
748.3 + 2.7 X<sub>1</sub> + 62.94 X<sub>2</sub> = 0  $\rightarrow (2)$ 

From (1)

$$X_{2} = -\left(\frac{485.6 + 65.64 X_{1}}{2.7}\right) \text{ putting in (2)}$$

$$748.3 + 2.7 X_{1} - 62.94 \left(\frac{485.6 + 65.64 X_{1}}{2.7}\right) = 0 \longrightarrow (2)$$

$$748.3 + 2.7 X_{1} - 11319.875 - 1530.141 X_{1} - 10571.575 - 1527.441 X_{1} = 0 \longrightarrow (3)$$

From (3) 
$$X_{2} = -\left(\frac{485.6 - 65.64 \times 6.921}{2.7}\right)$$
$$X_{2} = -11.592 \text{ KN}$$

Now put values of  $X_1$  and  $X_2$  in 5<sup>th</sup> column of S to get final number forces SF as given in last column of table. Apply equilibrium check to verify correctness of solution.

Insert Page No. 148-A

## **EQUILIBRIUM CHECKS:-**



$$\begin{split} & \sum FX = 0 \\ & 3.408 \ Cos\theta - H_A - 0 \end{split}$$

 $H_{A} = 2.045 \text{ KN}$ 

 $\sum Fy = 0$  $-6.726 + 4 + 3.408 Sin\theta = 0$ 0 = 0 Check is OK.





 $H_{\rm F} = + \ 6.955 \ {\rm KN}$ 

 $\sum Fy = 0$ 36 - 27.726 - 11.592 × Sin $\theta = 0$ 0 = 0 (check)

It means solution is correct. Now calculate vertical reactions and show forces in diagram.



## ANALYZED TRUSS

$$\begin{split} & \sum M_A \ = \ 0 \\ & V_F \times 6 - 20 \times 6 - 3 \times 16 - 6 \times 8 = 0 \end{split}$$

$$V_F = +36 \text{ KN}$$

$$\sum Fy = 0$$

$$V_A + V_F = 40 \text{ KN}$$

$$V_A = +4 \text{ KN}$$

## **EXAMPLE NO. 11:**



Compatibility Equations are:

$$\Sigma S. \frac{\partial S}{\partial HF} \cdot \frac{L}{AE} = 0$$
 (1) Partial differentiation of strain energy w.r.t.  $HF = \Delta H = 0.$  (Pin support)  

$$\Sigma S. \frac{\partial S}{\partial X} \cdot \frac{L}{AE} = 0$$
 (2) Partial differentiation of strain energy w.r.t.  $X =$  elongation of member CE due to  $X = 0.$ 

As before determine member forces Si in members by method of joints.

Joint (A)



36



$$\begin{split} &\sum Fy \ = \ 0 \\ &S_{DE} \ +36 \ -1.33 \ H_F + X \ Sin\theta \ - \ (15 \ -1.67 H_F \ ) \ Sin\theta \ = \ 0 \ \ by \ putting \ Sin\theta \ = \ 0.08 \\ &S_{DE} \ + \ 36 \ -1.33 \ H_F \ + \ 0.8 X \ -12 \ + \ 1.33 \ H_F \ = \ 0 \\ &S_{DE} \ = \ - \ 0.8 X \ -24 \end{split}$$

$$S_{DE} = - (\ 24 + 0.8 X)$$

Joint (C)



$$\sum FX = 0$$
  

$$S_{CD} + 3 + X \cos\theta = 0$$
  

$$\boxed{S_{CD} = -(3 + 0.6X)}$$
  

$$\sum Fy = 0$$
  

$$-20 - S_{BC} - X \sin\theta = 0$$
  

$$-20 - S_{BC} - 0.8X = 0$$
  

$$\boxed{S_{BC} = -(20 + 0.8X)}$$

Joint (D)



$$\Sigma FX = 0$$
  
3 + 0.6X - S<sub>BD</sub> Cos $\theta$  = 0  
3 + 0.6X - 0.6 S<sub>BD</sub> = 0

$$S_{BD} = (5 + X)$$

$$\sum Fy = 0$$
  
- 20 + 24 + 0.8X - S<sub>BD</sub> Sin $\theta$  = 0  
- 20 + 24 + 0.8X - (5 + X) 0.8 = 0  
- 20 + 24 + 0.8X - 4 - 0.8X = 0  
0 = 0 (check)

Calculation of  $H_F \& X_:$ -From the attached table, picking up the values of summations, we have.

$$\Sigma$$
. S.  $\frac{\partial S}{\partial H_F}$ .  $\frac{L}{AE} = 0 = (-1247.03 + 175.24 H_F - 4.5 \times X) 10^{-6}$ 

and

$$\Sigma$$
. S.  $\frac{\partial S}{\partial X}$ .  $\frac{L}{AE} = 0 = (460.6 - 4.5 \text{ H}_{\text{F}} + 65.64 \text{X}) 10^{-6}$ 

$$\begin{array}{rl} -1247.03 + 175.24 \text{ H}_{\text{F}} - 4.5 \text{X} = 0 & \rightarrow & (1) \\ + 460.6 - 4.5 \text{ H}_{\text{F}} + & 65.64 \text{X} = 0 & \rightarrow & (2) \end{array}$$

From (1)

$$X = \left(\frac{-1247.03 + 175.24 \text{ H}_{\text{F}}}{4.5}\right) \to (3)$$

Put in (2) to get H<sub>F</sub>

$$460.6 - 4.5 \text{ H}_{\text{F}} + 65.64 \left( \frac{-1247.03 + 175.24 \text{ H}_{\text{F}}}{4.5} \right) = 0$$

 $\begin{array}{l} 460.6-4.5 \ H_F-18190.01+2556.17 \ H_F=0 \\ -17729.41+2551.67 \ H_F\ =\ 0 \end{array}$ 

$$H_{\rm F} = 6.948 \ {\rm KN}$$

Put this value in 3 to get X.

$$\mathbf{X} = \left(\frac{-1247.03 + 175.24 \times 6.948}{4.5}\right) \tag{3}$$

or X = -6.541 KN Now calculate number Forces by putting the values of X and  $H_F$  in S expressions given in column 5 of the attached table. These final forces appear in last column for  $S_F$ .



Fig 2.52 ANALYZED TRUSS

Insert Page No. 153-A

Equilibrium checks for the accuracy of calculated member Forces:-



## EXAMPLE NO. 12:-

By the unit load-method analyze the internally indeterminate truss shown below. Take the forces in members  $L_1U_2$  and  $U_2L_3$  as the redundants.

*Note:* The same truss has already been solved in Example No. 9, by taking  $L_1U_2$  and  $L_2U_3$  as redundants.

$$E = 200 \times 10^6 \text{ KN/m}^2$$

## **SOLUTION:-**



## **Compatibility equations are :**

$$\Delta X_{1} + \Delta X_{1}R_{1} + \Delta X_{1}R_{2} = 0 \rightarrow (1) \qquad \text{Here } X_{1} = R_{1} \\ X_{2} = R_{2} \\ \text{Deflection created by applied loads and redundants shall be zero.} \\ \Delta X_{2}L + \Delta X_{2}R_{1} + \Delta X_{2}R_{2} = 0 \rightarrow (2) \\ \Delta X_{1}L = \sum \cdot \frac{F'U_{1}L}{AE} \quad (\text{Change in length of first redundant member by applied loads}) \\ \Delta X_{1}R_{1} = \sum \left(\frac{U_{1}^{2}L}{AE}\right) X_{1} \quad (\text{Change in length in first redundant member due to first redundant force}) \\ \Delta X_{1}R_{2} = \sum \left(\frac{U_{1}U_{2}L}{AE}\right) \cdot X_{2} \quad (\text{Change in length in first redundant member due to second redundant force}) \\ \Delta X_{2}L = \sum \frac{F'U_{2}L}{AE} \quad (\text{Change in second redundant member due to applied load.}) \\ \Delta X_{2}R_{1} = \sum \left(\frac{U_{1}U_{2}L}{AE}\right) \cdot X_{1} \quad (\text{Change in length of second redundant member due to first redundant force.}) \\ \Delta X_{2}R_{2} = \sum \left(\frac{U_{2}^{2}L}{AE}\right) \cdot X_{2} \quad (\text{Change in length of second redundant member due to redundant force in it.}) \\ \Delta X_{2}R_{2} = \sum \left(\frac{U_{2}^{2}L}{AE}\right) \cdot X_{2} \quad (\text{Change in length of second redundant member due to redundant force in it.}) \\ \Delta X_{2}R_{2} = \sum \left(\frac{U_{2}^{2}L}{AE}\right) \cdot X_{2} \quad (\text{Change in length of second redundant member due to redundant force in it.}) \\ \Delta X_{2}R_{2} = \sum \left(\frac{U_{2}^{2}L}{AE}\right) \cdot X_{2} \quad (\text{Change in length of second redundant member due to redundant force in it.}) \\ \Delta X_{2}R_{2} = \sum \left(\frac{U_{2}^{2}L}{AE}\right) \cdot X_{2} \quad (\text{Change in length of second redundant member due to redundant force in it.}) \\ \Delta X_{2}R_{2} = \sum \left(\frac{U_{2}^{2}L}{AE}\right) \cdot X_{2} \quad (\text{Change in length of second redundant member due to redundant force in it.}) \\ \Delta X_{2}R_{2} = \sum \left(\frac{U_{2}^{2}L}{AE}\right) \cdot X_{2} \quad (\text{Change in length of second redundant member due to redundant force in it.}) \\ \Delta X_{2}R_{3} = \sum \left(\frac{U_{2}^{2}L}{AE}\right) \cdot X_{3} \quad (\text{Change in length of second redundant member due to redundant force in it.}) \\ \Delta X_{3} = \sum \left(\frac{U_{3}^{2}L}{AE}\right) \cdot X_{3} \quad (\text{Change in length of second redundant member due to redundant force in it.}) \\ \Delta X_{3} = \sum \left(\frac{U_{3}^{2}L}{AE}\right) \cdot X_{3} \quad (\text{Change in length of second redundant me$$

Picking up the above deformations from the table (158–A) and calculate final member forces by following formula.

$$F = F' + U_1 X_1 + U_2 X_2$$

Forces in chord members and inclineds are determined by the method of moments and shears as explained already, while for verticals method of joints has been used.

Evaluation of force in verticals of F' – Diagram

(Joint L<sub>2</sub>)



 $\sum FX = 0$ 85.5 - 76.5 + 52.5 Sin $\theta$  - 67.5 Sin $\theta$  = 0 85.5 - 76.5 + 52.5 × 0.6 - 67.5 × 0.6 = 0 0 = 0 (Check)

$$\begin{split} &\sum Fy + 0 \\ &U_2L_2 + 52.5\ Cos\theta + 67.5\ Cos\ \theta - 96 = 0 \\ &U_2L_2 = -52.5\times 0.8 - 67.5\times 0.8 + 96 = 0 \end{split}$$

$$U_2L_2 = 0$$

Insert Page No. 158-A

Picking the following values from attached table (Table for example No.12)  $\Delta X_1 L = +1.009 \times 10^{-3}$ 

 $\begin{array}{l} \Delta X_1 R_1 \ = \ + \ 125.7 \times 10^{-6} \ X_1 \ = \ + \ 0.1257 \times 10^{-3} \ X_1 \\ \Delta X_1 R_2 \ = \ + \ 32 \times 10^{-6} \ X_2 \ = \ + \ 0.032 \times 10^{-3} \ X_2 \\ \Delta X_2 L \ = \ - \ 0.171 \times 10^{-3} \\ \Delta X_2 R_1 \ = \ + \ 32 \times 10^{-6} \ X_1 \ = \ + \ 0.032 \times 10^{-3} \ X_1 \\ \Delta X_2 R_2 \ = \ + \ 125.7 \times 10^{-6} \ X_2 \ = \ + \ 0.1257 \times 10^{-3} \ X_2 \end{array}$ 

Putting these in compatibility equals.

$$1.009 \times 10^{-3} + 0.1257 \times 10^{-3} X_1 + 0.032 \times 10^{-3} X_2 = 0$$
(1)  
- 0.171 × 10^{-3} + 0.032 × 10^{-3} X1 + 0.1257 × 10^{-3} X2 = 0 (2)

Simplify

$$1.009 + 0.1257 X_1 + 0.032 X_2 = 0 \longrightarrow (1)$$
  
- 0.171 + 0.032 X<sub>1</sub> + 0.1257X<sub>2</sub> = 0  $\rightarrow$  (2)

From (1) 
$$X_1 = \left(\frac{-1.009 - 0.032 X_2}{0.1257}\right) \rightarrow (3)$$

Put in (2) & solve for  $X_2$ 

$$-0.171 + 0.032 \left(\frac{-1.009 - 0.032 X_2}{0.1257}\right) + 0.1257 X_2 = 0$$

$$\begin{array}{l} - \ 0.171 - 0.257 - 8.146 \times 10^{^{-3}} \, X_2 + 0.1257 X_2 = 0 \\ - \ 0.428 + 0.1176 \, X_2 = 0 \end{array}$$

$$\mathbf{X}_2 = \frac{0.428}{0.1176}$$

$$X_2 = 3.64 \text{ KN}$$

Put this in equation (3) to get  $X_1$ 

(3) 
$$\Rightarrow X_1 = \left(\frac{-1.009 - 0.032 \times 3.64}{0.1257}\right)$$
  
 $X_1 = -8.95 \text{ KN}$ 

So final forces in members are calculated by the following given formula.

$$\begin{split} F &= F' + U_1 X_1 + U_2 X_2 \\ FLoL_1 &= 76.5 + 0 + 0 = + 76.5 \text{ KN} \\ FL_1 L_2 &= 76.5 + (-0.6) (-8.95) + 0 = + 81.87 \text{ KN} \\ FL_2 L_3 &= 85.5 + 0 + 3.64) (-0.6) = + 83.32 \text{ KN} \\ FL_3 L_4 &= 85.5 + 0 + 0 = + 85.5 \text{ KN} \\ FU_1 U_2 &= -117 + (-0.6) (-8.95) + 0 = - 111.63 \text{ KN} \\ FU_2 U_3 &= -117 + 0 + (-0.6) (3.64) = - 119.18 \text{ KN} \\ FU_1 L_1 &= + 48 + (-0.8) (-8.95) + 0 = + 55.16 \text{ KN} \\ FU_2 L_2 &= 0 + (-0.8) (-8.95) + (-0.8) (3.64) = + 4.25 \text{ KN} \end{split}$$

$$\begin{split} FU_3\,L_3 &= +\ 72 + 0 + (-\ 0.8)\ (3.64) = +\ 69.09\ KN\\ Flo\ U_1 &= -\ 127.5 + 0 + 0 = -\ 127.5\ KN\\ FU_1\,L_2 &= +\ 67.5 + (1)\ (-\ 8.95) + 0 = -\ 8.95\ KN\\ FL_1\,U_2 &= 0 + (1)\ (-\ 8.95) + 0 = -\ 8.95\ KN\\ FU_2\,L_3 &= 0 + 0 + (1)\ (3.64) = +\ 3.64\ KN\\ FL_2\,U_3 &= 52.5 + 0 + (1)\ (3.64) = +\ 56.14\ KN\\ FU_3\,L_4 &= -\ 142.5 + 0 + 0 = -\ 142.5\ KN \end{split}$$

#### **CHECK ON FORCE VALUES**

We may apply check at random at any joint. If solution is correct, equilibrium checks will be satisfied at all joint.

Joint Lo.

 $\sum FX = 0$ 76.5 - 127.5 Sin $\theta = 0$ 76.5 - 127.5 Sin $\theta = 0$ 76.5 - 127.5 × 0.6 = 0 0 = 0  $\sum Fy = 0$ 102 - 127.5 × 0.8 = 0 0 = 0 OK. Results seem to be correct.

The credit for developing method of least work goes to Alberto Castiglianos who worked as an engineer in Italian Railways. This method was presented in a thesis in partial fulfillment of the requirement for the award of diploma engineering of associate engineer. He published a paper for finding deflections which is called Castiglianos first theorem and in consequence thereof, method of least work which is also known as Castiglianos second theorem. Method of least work also mentioned earlier in a paper by an Italian General Menabrea who was not able to give a satisfactory proof. Leonard Euler had also used the method about 50 years ago for derivation of equations for buckling of columns wherein, Daniel Bernolli gave valuable suggestion to him.

Method of least work or Castiglianos second theorem is a very versatile method for the analysis of indeterminate structures and specially to trussed type structures. The method does not however, accounts for erection stresses, temperature stresses or differential support sinking. The reader is advised to use some other method for the analysis of such indeterminate structures like frames and continuos beams.

It must be appreciated in general, for horizontal and vertical indeterminate structural systems, carrying various types of loads, there are generally more than one structural actions present at the same time including direct forces, shear forces, bending moments and twisting moments. In order to have a precise analysis all redundant structural actions and hence strain energies must be considered which would make the method laborious and cumbersome. Therefore, most of engineers think it sufficient to consider only the significant strain energy. The reader should know that most of structural analysis approaches whether classical or matrix methods consider equilibrium of forces and displacement/strain compatibility of members of a system.

The basis of the method of consistent deformation and method of least work are essentially the same. In consistent deformation method, the deformation produced by the applied loads are equated to these produced by the redundants. This process usually results in the evolution of redundants. However, in the method of least work, total strain energy expression of a structural system in terms of that due to known applied loads and due to redundants is established. Then the total strain energy is partially differentiated with respect to redundant which ultimately result in the evolution of the redundant. It must be appreciated that, for indeterminate structural system like trusses, the unknown redundants maybe external supports reaction or the internal forces or both. And it may not be very clear which type of redundants should be considered as the amount of work involved in terms of requisite calculation may vary. Therefore, a clever choice of redundants (or a basic determinate structure as was the case with consistent deformation method) may often greatly reduce the amount of work involved.

There is often a debate going on these days regarding the utility or justification of classical structural analysis in comparison to the computer method of structural analysis. It is commented that in case of classical methods of structural analysis the student comes across basic and finer points of structural engineering after which a computer analysis of a complex structure maybe undertaken.

In the absence of basic knowledge of classical structural analysis, the engineer maybe in a difficult position to justify to computer results which are again to be checked against equilibrium and deformation compatibility only.

## EXAMPLE NO. 13:

The procedure for analysis has already been given. Utilizing that procedure, analyze the following truss by the method of least work. Areas in () carry the units of  $10^{-3}$  m<sup>2</sup> while the value of E can be taken as  $200 \times 10^{6}$  KN/m<sup>2</sup>.



where i = total degree of indeterminacy

b = number of bars.

r = total number of reactive components which the support can provide.

b + r = 2j

 $10 + 3 > 2 \times 6$  13 > 12 so i= 1 . First degree internal indeterminancy.  $F^{2}L$ 

 $U = \frac{F^2 L}{2 AE}$  Strain energy due to direct forces induced due to applied loads in a BDS Truss.

$$\frac{\partial U}{\partial X} = F.\frac{\partial F}{\partial X} \cdot \frac{L}{AE} = 0$$

*Note:* We select the redundants in such a way that the stability of the structure is not effected. Selecting member EC as redundant.



F-diagram B.D.S. under the action of applied loads & redundant.



Method of moments and shears has been used to find forces in BDS due to applied loads. A table has been made. Forces vertical in members in terms of redundant X may be determined by the method of joints as before. From table.

$$\Sigma F. \frac{\partial F}{\partial x} \cdot \frac{L}{AE} = 0 = -331.22 \times 10^{-6} + 51.49 \times 10^{-6} X$$
  
or  $-331.22 + 51.49 X = 0$   
 $X = +6.433 \text{ KN}$ 

The final member forces are obtained as below by putting value of X in column 5 of the table.

Member	Force (KN)
AB	+ 5
BC	+5.45
CD	+ 10
EF	- 9.55
BE	+0.45
CF	+ 10.45
CE	+ 6.43
BF	- 0.64
AE	- 7.07
DF	- 14.14

Insert page No. 164-A

CHECK.

Joint A.



- $\sum FX = 0$ 5 - 7.07 Cos $\theta$  = 0 5 - 7.07 × 0.707 = 0 0 = 0  $\sum Fy = 0$ - 7.07 × 0.707 + 5 = 0 0 = 0 Check is OK.
- **EXAMPLE NO. 14**:- Analyze the following symmetrically loaded second degree internally indeterminate truss by the method of least work. Areas in () are  $10^{-3}m^2$ . The value of E can be taken as  $200 \times 10^6$  KN/m<sup>2</sup>



Selecting member BD and Before as redundants.



## **SOLUTION:**



<u>Note</u> :- By virtue of symmetry, we can expect to have same values for  $X_1$  and  $X_2$ . It is known before hand.

SFD and BMD in BDS due to applied loads are shown above.

As in previous case determine member forces in BDS due to applied loads by the method of moments shears while method of joints may be used to determine member forces due to redundants acting separately. Apply super position principal. Then these are entered in a table given.

Summation of relavant columns due to X1 and X2 gives two equations from which these can be calculated. Putting values from table and solving for X1 and X2.

 $\begin{array}{l} [-2.65 \times 10^{-3} (7.5 - 0.707 X_{1}) - 2.65 \times 10^{3} (-0.707 X_{1}) - 3.53 \times 10^{-3} (-0.707 X_{1}) \\ -3.53 \times 10^{-3} (15 - 0.707 X_{1} - 0.707 X_{2}) + 10.6 \times 10^{-3} (-10.6 + X_{1}) + 10.6 \times 10^{-3} (X_{2}) ]10^{-3} = 0 \end{array}$ 

Put  $X_2$  in equation 3 to get  $X_1$ . The final member forces are given in last column. These are obtained by putting values of  $X_1$  and  $X_2$ , whichever is applicable, in column 5 of the table.

 $X_2 = +5.716 \text{ KN}$ 

Insert Page No. 166-A

Then 
$$X_1 = \left(\frac{185.185 - 2.50 \times 5.716}{29.898}\right)$$
  
eck.  
 $X_1 = +5.716 \text{ KN}$   
eck.  
 $4.04$   
 $4.884$   
 $0$   
 $7.5$   
 $\Sigma FX = 0$   
 $3.459 - 4.884 \times Cos\theta = 0$   
 $3.459 - 4.884 \times 0.707 = 0$   
 $0 = 0$   
 $\Sigma Fy = 0$   
 $7.5 - 4.04 - 4.884 \times 0.707 = 0$ 

0 = 0 Checks are satisfied. Results are OK.

**EXAMPLE NO. 15:** Analyze the following internally indeterminate truss by the method of least work. Areas in () are  $10^{-3}$ m<sup>2</sup>. The value of E can be taken as  $200 \times 10^{6}$  KN/m<sup>2</sup>.

#### SOLUTION:-

b = 13, r = 3, j = 7 so degree of indeterminacy I = (b + r) -2j = 2Choosing members EB and BG as redundants, forces due to loads have been determined by the method of moments and shears for the BDS and are entered in a table. While forces due to redundants  $X_1$  and  $X_2$ .



Equilibrium Check.



Member Forces Due to Redundants Only.

Please number that due to separate action of redundants  $X_1$  and  $X_2$  member forces will be induced only in the square whose inclineds are  $X_1$  and  $X_2$ . There will be no reaction at supports.

Joint D:-





$$BF = -0.707X_1 - 0.707X_2$$

Joint A.



$$\sum FX = 0$$
  
- 0.707 X<sub>1</sub> + AF Cos  $\theta = 0$ 

$$AF = X_1$$

$$\Sigma Fy = 0$$

$$AE + AF \sin \theta = 0$$

$$AE = -0.707X_1$$

Joint E.

$$\sum FX = 0$$
  
EF + X<sub>1</sub> Cos  $\theta = 0$   
EF = -0.707 X<sub>1</sub>  
$$\sum Fy = 0$$

$$2.19 = 0$$
  
0.707 X<sub>1</sub> - 0.707 X<sub>1</sub> = 0  
0 = 0 (Check)

Entering the values of summations from attached table, we have.

$$\Sigma \text{ F. } \frac{\partial F}{\partial X_1} \cdot \frac{L}{AE} = 0 = -229.443 \times 10^{-6} + 29.848 \times 10^{-6} X_1 + 2.45 \times 10^{-6} X_2$$
$$\Sigma \text{ F. } \frac{\partial F}{\partial X_2} \cdot \frac{L}{AE} = 0 = -168.9 \times 10^{-6} + 2.45 \times 10^{-6} X_1 + 29.848 \times 10^{-6} X_2$$

Simplifying

$$-229.443 + 29.848 X_1 + 2.45 X_2 = 0 \longrightarrow (1)$$

$$-168.9 + 2.45 X_1 + 29.848 X_2 = 0 \qquad \rightarrow (2)$$

From (1)

$$X_{1} = \left(\frac{-2.45 X_{2} + 229.443}{29.848}\right) \longrightarrow (3)$$
  
Put in (2) & solve for X<sub>2</sub>  
 $(-2.45 X_{2} + 229.443)$ 

$$-168.9 + 2.45 \left(\frac{-2.45 X_2 + 229.443}{29.848}\right) + 29.848 X_2 = 0$$
  
-168.9 - 0.201 X<sub>2</sub> + 18.833 + 29.848 X<sub>2</sub> = 0  
-150.067 + 29.647 X<sub>2</sub> = 0  
X<sub>2</sub> = \frac{150.067}{29.647}

$$X_2 = +5.062 \text{ KN}$$

Insert page No. 170-A

So 
$$X_1 = \frac{-2.45 \times 5.062 + 229.443}{29.848}$$
 by putting value of  $X_2$  in (3)

$$X_1 = +7.272 \text{ KN}$$

# **EQUILIBRIUM CHECKS :-**



Joint B:-



$$\sum FX = 0$$
  
6.421 + 5.062 Cos $\theta$  - 7.272 Cos $\theta$  - 4.859 = 0  
0 = 0  
$$\sum Fy = 0$$
  
6.28 - 15 + 5.062 Sin $\theta$  + 7.272 Sin $\theta$  = 0  
0 = 0 The results are OK.

Joint C:-



 $\sum FX = 0$ 5 + 2.008 Cos $\theta$  - 6.421 = 0 0 = 0  $\sum Fy = 0$ 1.421 - 2.008 Sin $\theta$  = 0

0 = 0 Results are OK.